



ROBOT CONTROL

Anno immatricolazione	2017/2018
Anno offerta	2018/2019
Normativa	DM270
SSD	ING-INF/04 (AUTOMATICA)
Dipartimento	DIPARTIMENTO DI INGEGNERIA INDUSTRIALE E DELL'INFORMAZIONE
Corso di studio	ELECTRONIC ENGINEERING
Curriculum	PERCORSO COMUNE
Anno di corso	2°
Periodo didattico	Secondo Semestre (06/03/2019 - 14/06/2019)
Crediti	6
Ore	45 ore di attività frontale
Lingua insegnamento	
Tipo esame	SCRITTO E ORALE CONGIUNTI
Docente	FERRARA ANTONELLA (titolare) - 6 CFU
Prerequisiti	Knowledge acquired in previous courses in Automatic Control and Mathematical Methods in Engineering.
Obiettivi formativi	The course provides the basic methodological tools to model and control industrial robots.
Programma e contenuti	Modelling of robotic systems: Structure of robotic manipulators. Classification. The joint space and the operational space. Direct kinematics. Inverse kinematics. Differential kinematics. Euler angles. Relationship between geometrical and analytical Jacobian. Dynamic modeling. Robot control: Planning. Motion control in the joint space (decentralized and centralized) and in the operational space (inverse dynamics). Interaction

	control: force control, hybrid force/position control.
Metodi didattici	Lectures (hours/year in lecture theatre): 45 Practical class (hours/year in lecture theatre): 0 Practicals / Workshops (hours/year in lecture theatre): 0
Testi di riferimento	Lecture notes Robotics: Modelling, Planning and Control (Advanced Textbooks in Control and Signal Processing). Bruno Siciliano, Lorenzo Sciavicco, Luigi Villani, Giuseppe Oriolo. Springer.
Modalità verifica apprendimento	Closed-book, closed-notes, 2 hour written exam consisting of 3 sections assessing knowledge and understanding of the course topics and ability to apply them in a problem solving context. Each section will be independently graded. Threshold to pass is 18/30 and maximum mark is 30/30 cum laude. The final mark is obtained as the weighted mean of marks given to each section of the written exam. Example of a written exam: http://sisdin.unipv.it/labsisdin/teaching/courses/robcon/files/Robot_Control_Exam_Example.pdf
Altre informazioni	
Obiettivi Agenda 2030 per lo sviluppo sostenibile	\$lbl_legenda_sviluppo_sostenibile